

# Implementing malloc

Science

Computer  
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CS 351: Systems Programming  
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the API:

```
void *malloc(size_t size);
```

```
void free(void *ptr);
```

```
void *realloc(void *ptr, size_t size);
```



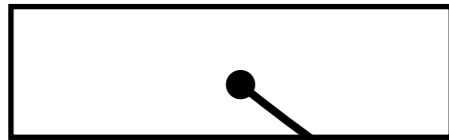
```
void *malloc(size_t size);
```

- returns a pointer to the payload (of min length **size** bytes) of a memory block
- the payload area is *off-limits* to the DMA until released by the user

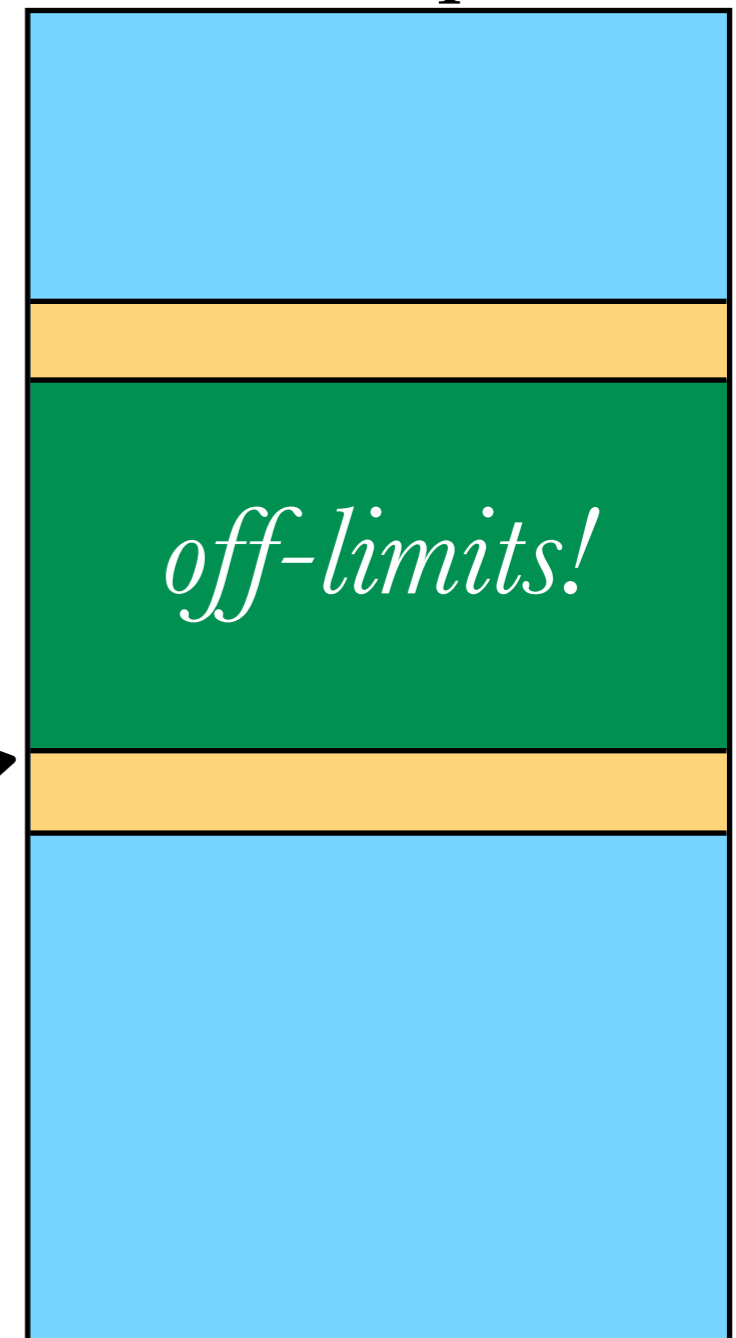


## Heap

```
void *p = malloc(N)
```



*at least*  
N bytes



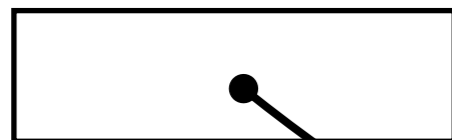
```
void free(void *ptr);
```

- indicates to the DMA that the payload pointed to by `ptr` can be reused
- value of `ptr` must have been returned by a previous call to `malloc` (or variant)

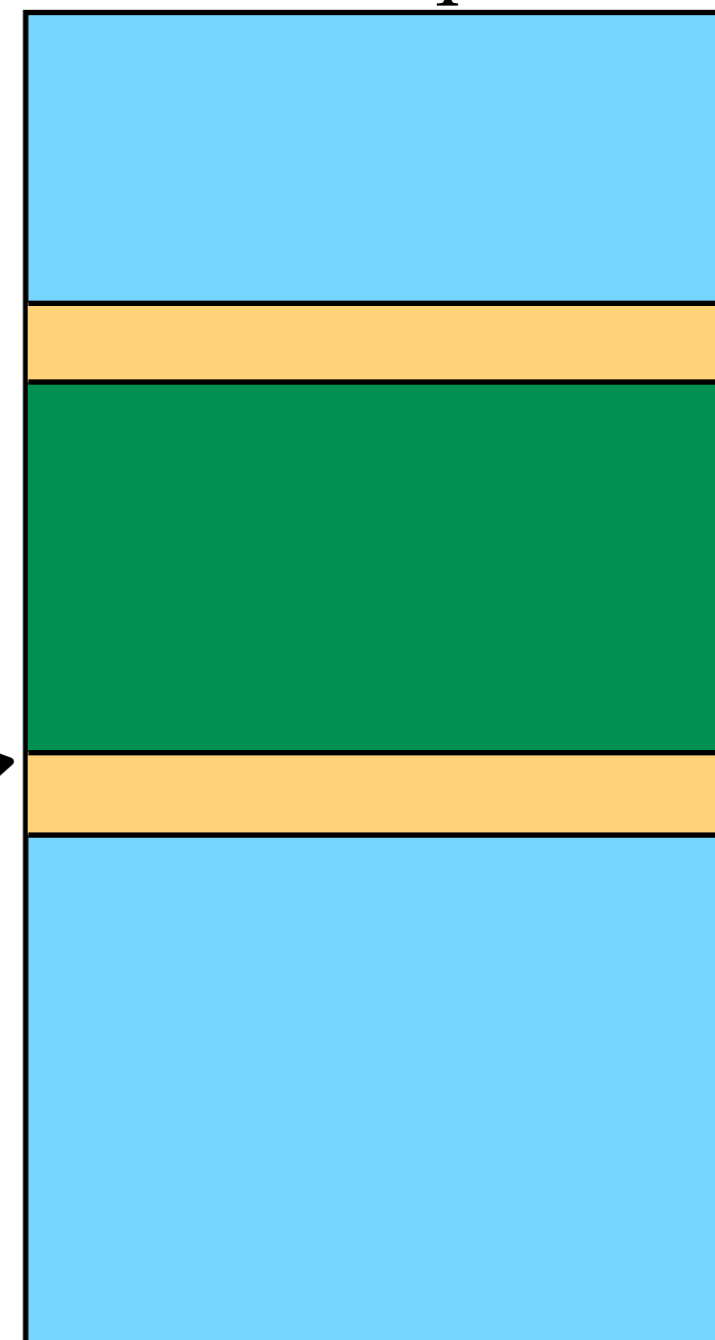


## Heap

```
void *p = malloc(N)
```



```
free(p)
```



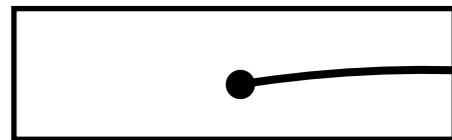
```
void *realloc(void *ptr, size_t size);
```

- request to resize payload region pointed to by `ptr` to `size`
- *DMA may* allocate a new block
  - old data is copied to new payload
  - old payload is freed

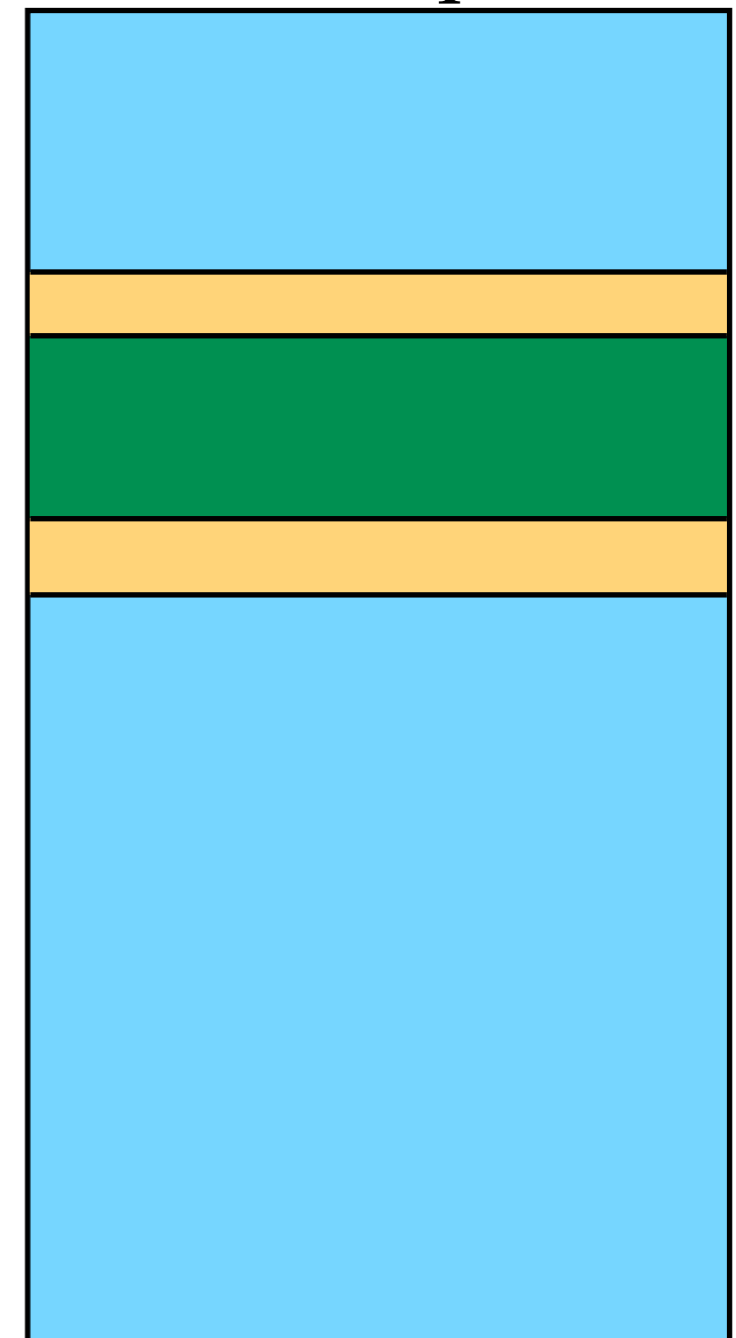


## Heap

```
void *p = malloc(N)
```



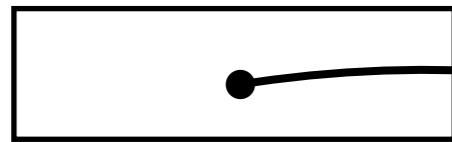
```
realloc(p, N+k)
```





option 1: grow in place

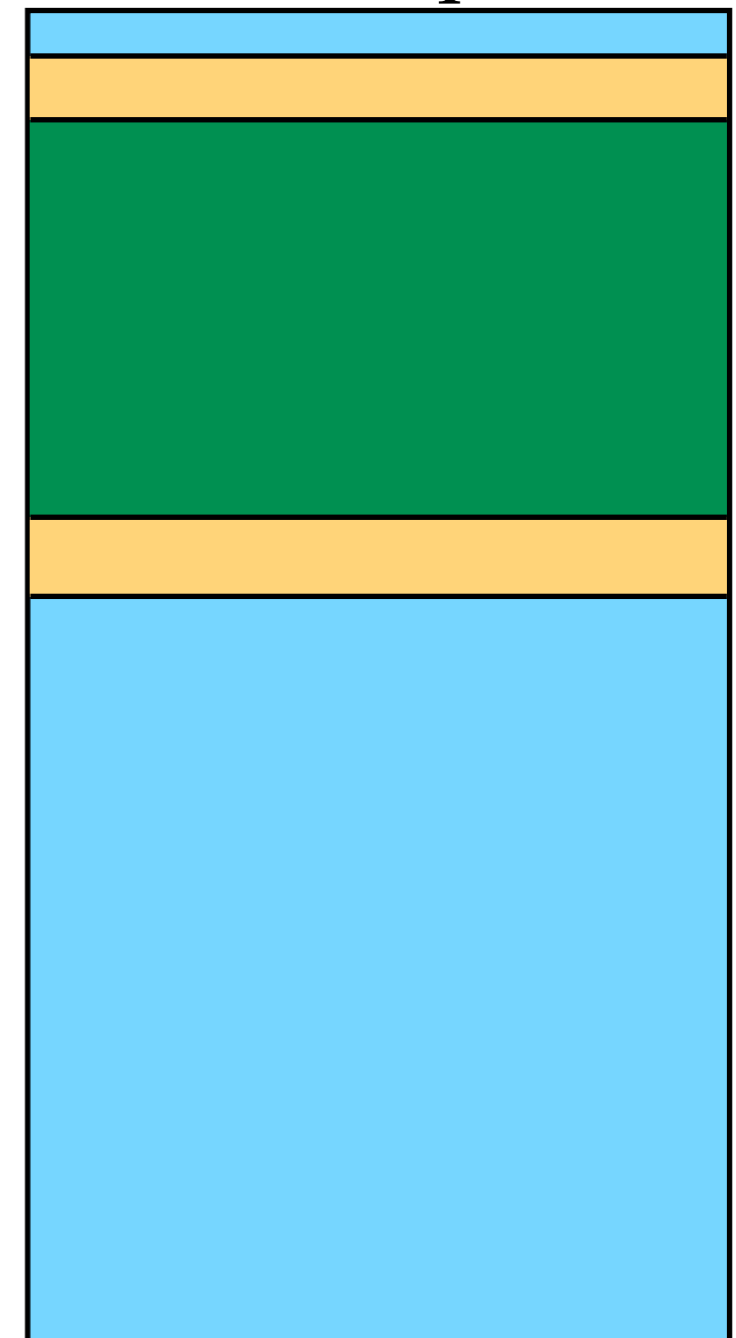
```
void *p = malloc(N)
```



*at least*  
N+k bytes

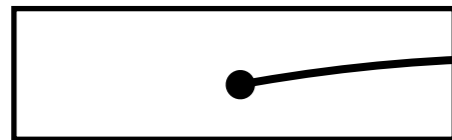
```
realloc(p, N+k)
```

Heap



option 2: new allocation

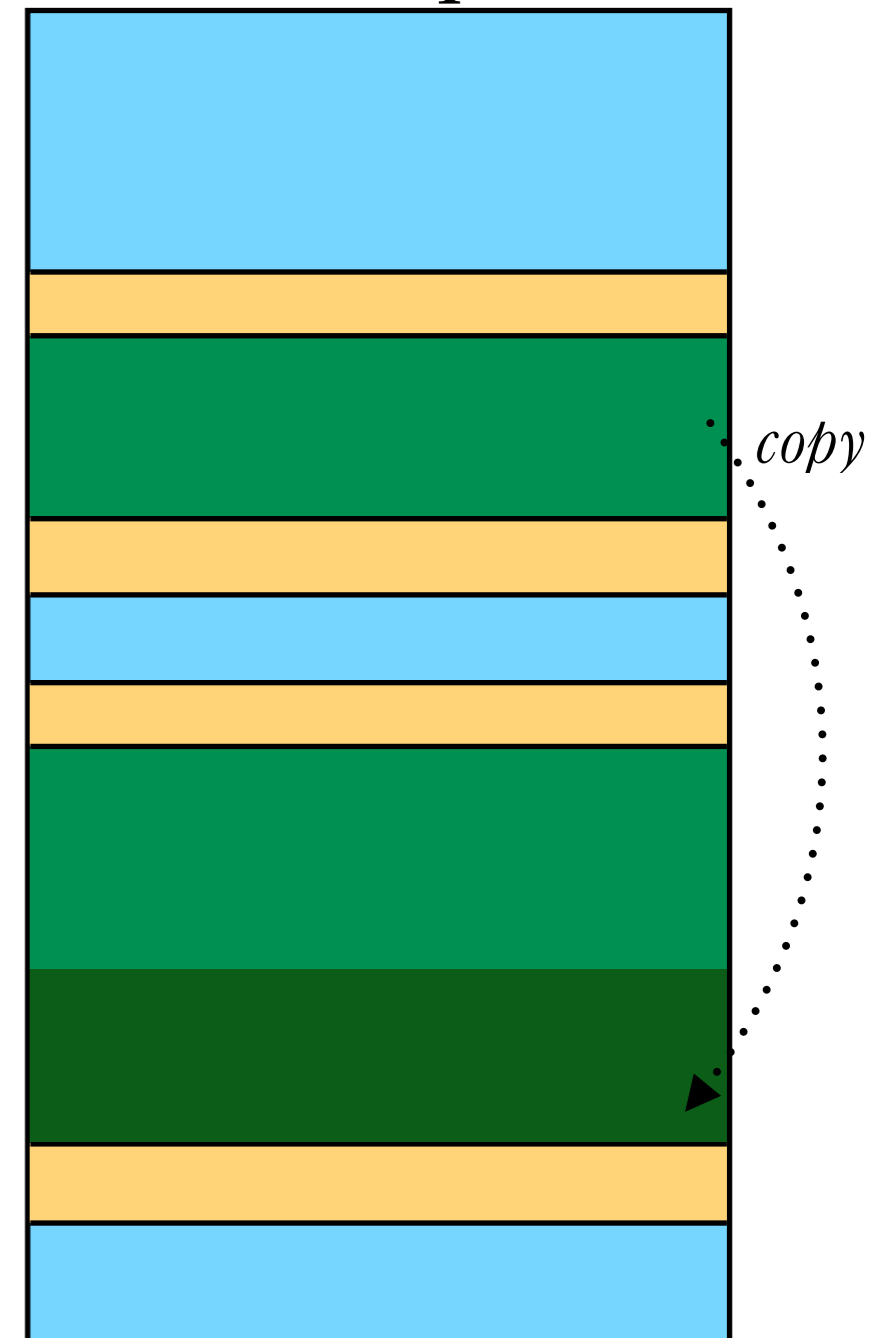
```
void *p = malloc(N)
```



```
realloc(p, N+k)
```

*at least*  
N+k bytes

Heap



note: k may be negative!



basic implementation issues:

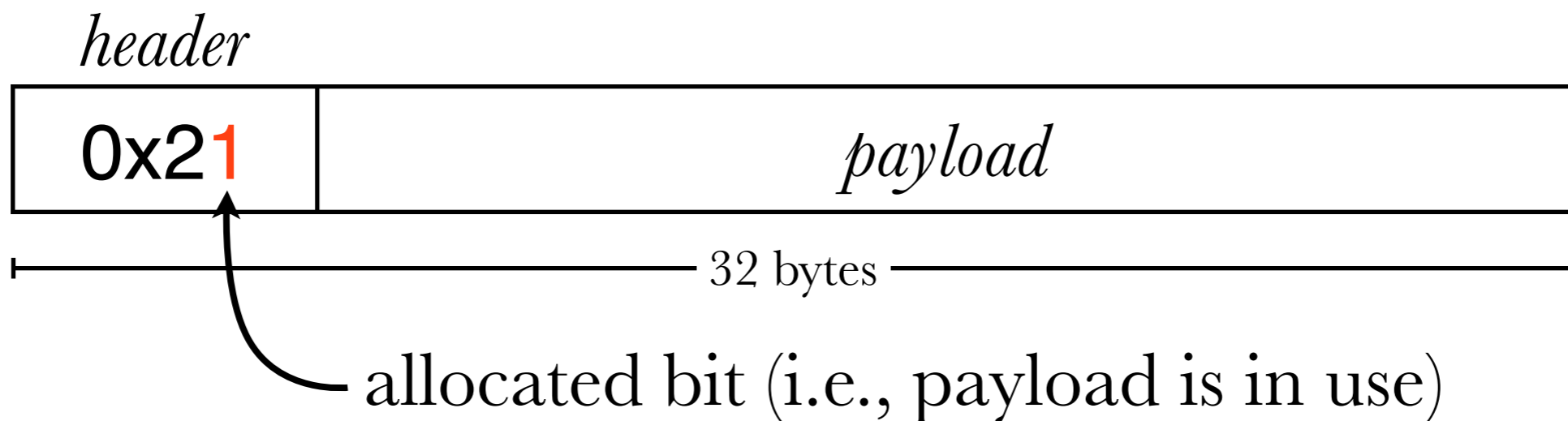
- tracking block metadata
- searching for and managing free space
- performing allocations



typical metadata = *size & allocation status*

- usually store in a block “header”
- if size is aligned to  $> 2$  bytes, can use *bottom bit* of size for *allocated bit*
  - 1 for allocated, 0 for free





after free:





important: payload should be *aligned*  
(i.e., begin on multiple of alignment size)

- usually means that header & block also be aligned

e.g., Linux requires 8-byte alignment



```
#define ALIGNMENT 8 // must be a power of 2
```

```
#define ALIGN(size) (((size) + (ALIGNMENT-1)) & ~(ALIGNMENT-1))
```

```
for (i=1; i<=32; i+=2) {  
    printf("ALIGN(%d) = %d\n",  
        i, ALIGN(i));
```



```
ALIGN(1) = 8  
ALIGN(3) = 8  
ALIGN(5) = 8  
ALIGN(7) = 8  
ALIGN(9) = 16  
ALIGN(11) = 16  
ALIGN(13) = 16  
ALIGN(15) = 16  
ALIGN(17) = 24  
ALIGN(19) = 24  
ALIGN(21) = 24  
ALIGN(23) = 24  
ALIGN(25) = 32  
ALIGN(27) = 32  
ALIGN(29) = 32  
ALIGN(31) = 32
```



```
#define ALIGNMENT 8 // must be a power of 2

#define ALIGN(size) (((size) + (ALIGNMENT-1)) & ~(ALIGNMENT-1))

#define SIZE_T_SIZE (ALIGN(sizeof(size_t))) // header size

// super-naive allocator
void *malloc(size_t size) {
    size_t blk_size = ALIGN(size + SIZE_T_SIZE);
    size_t *header = sbrk(blk_size);
    *header = blk_size | 1; // mark allocated bit
    return (char *)header + SIZE_T_SIZE;
}

void free(void *ptr) {
    size_t *header = (char *)ptr - SIZE_T_SIZE;
    *header = *header & ~1L; // unmark allocated bit
}
```

this implementation doesn't reuse blocks!





to reuse blocks, must search the heap  
for a free block  $\geq$  required size

```
void *find_fit(size_t size) {
    size_t *header = heap_start();
    while (header < heap_end()) {
        if (!(*header & 1) && *header >= size)
            return header;
        header = (char *)header + (*header & ~1L);
    }
    return NULL;
}
```

```
void *malloc(size_t size) {
    size_t blk_size = ALIGN(size + SIZE_T_SIZE);
    size_t *header = find_fit(blk_size);
    if (header) {
        *header = *header | 1;
    } else {
        header = sbrk(blk_size);
        *header = blk_size | 1;
    }
    return (char *)header + SIZE_T_SIZE;
}
```



```
void *malloc(size_t size) {
    size_t blk_size = ALIGN(size + SIZE_T_SIZE);
    size_t *header = find_fit(blk_size);
    if (header) {
        *header = *header | 1;
    } else {
        header = sbrk(blk_size);
        *header = blk_size | 1;
    }
    return (char *)header + SIZE_T_SIZE;
}
```

very inefficient — when re-using a block,  
always occupies the *entire block*!

- better to *split* the block if possible and  
reuse the unneeded part later



```
void *malloc(size_t size) {
    size_t blk_size = ALIGN(size + SIZE_T_SIZE);
    size_t *header = find_fit(blk_size);
    if (header) {
        *header = *header | 1;
    } else {
        header = sbrk(blk_size);
        *header = blk_size | 1;
    }
    return (char *)header + SIZE_T_SIZE;
}
```

---

```
void *malloc(size_t size) {
    size_t blk_size = ALIGN(size + SIZE_T_SIZE);
    size_t *header = find_fit(blk_size);
    if (header && blk_size < *header)
        // split block if possible (FIXME: check min block size)
        *((size_t *)((char *)header + blk_size) = *header - blk_size;
    else
        header = sbrk(blk_size);
    *header = blk_size | 1;
    return (char *)header + 8;
}
```



```
void *find_fit(size_t size) {
    size_t *header = heap_start();
    while (header < heap_end()) {
        if (!(*header & 1) && *header >= size)
            return header;
        header = (char *)header + (*header & ~1L);
    }
    return NULL;
}
```

we call this an *implicit list* based DMA

- navigating through blocks using sizes
- $O(n)$  search, where  $n = \#$  blocks
- $n$  comprises allocated & free blocks!



```
void *find_fit(size_t size) {  
    size_t *header = heap_start();  
    while (header < heap_end()) {  
        if (!(*header & 1) && *header >= size)  
            return header;  
        header = (char *)header + (*header & ~1L);  
    }  
    return NULL;  
}
```

to tune utilization & throughput, may  
pick from different search heuristics

- *first-fit* (shown above)
- *next-fit* (requires saving last position)
- *best-fit* ( $\Theta(n)$  time)

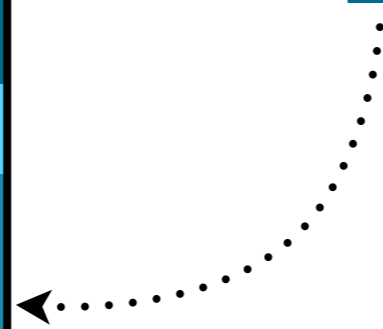




first fit:



request ①



*search start*  
*heap start*



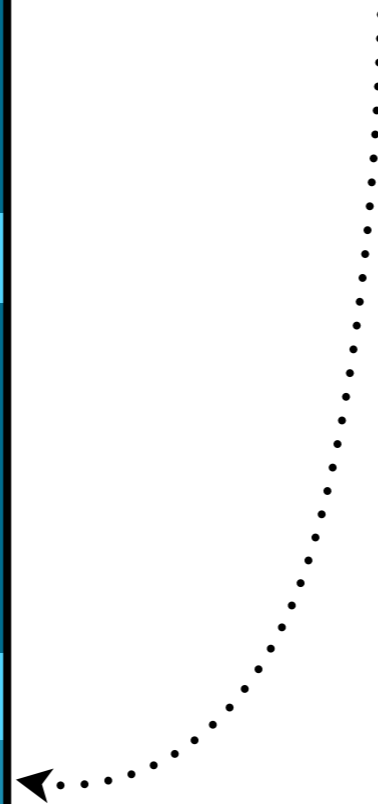


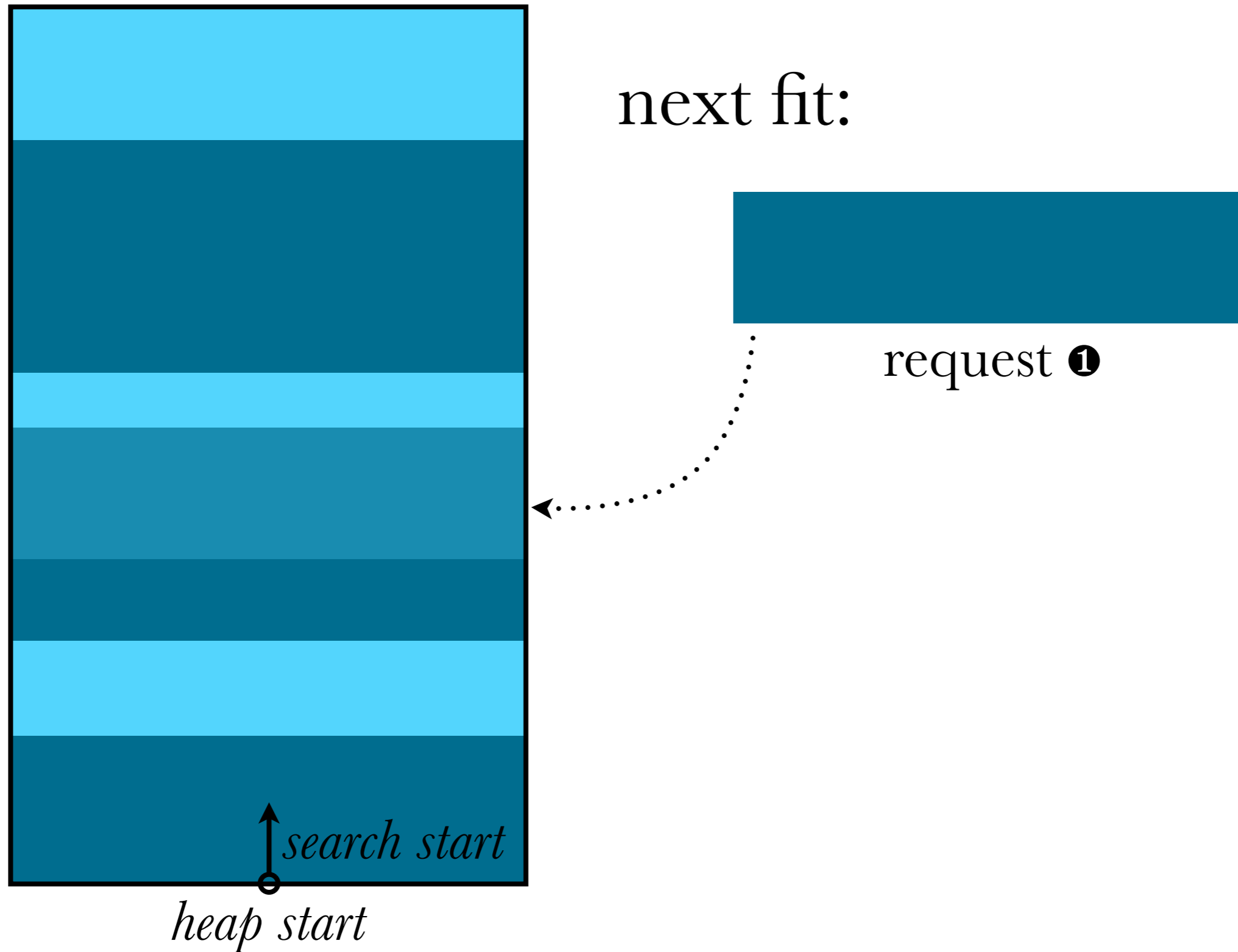
*heap start*

first fit:

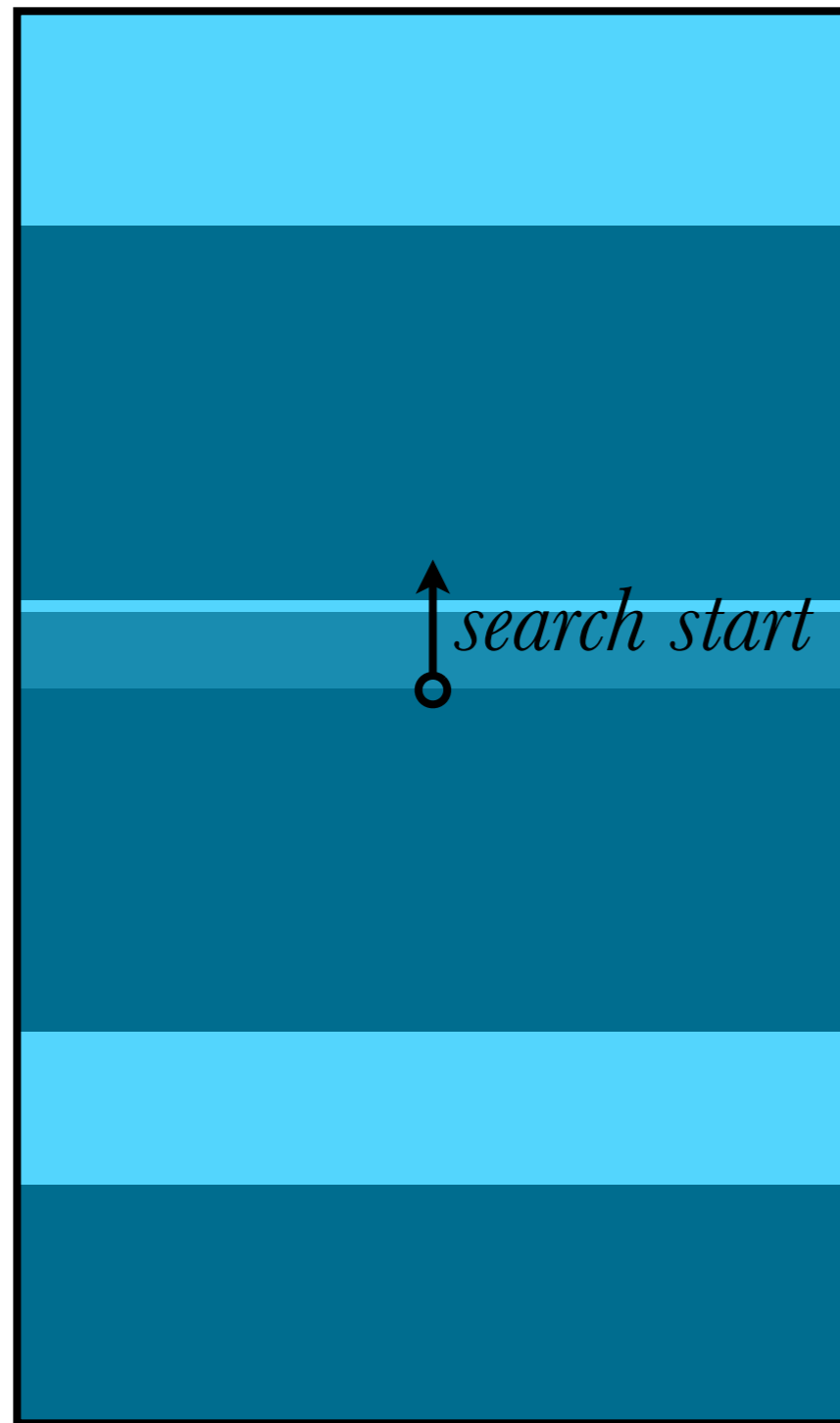


request ②





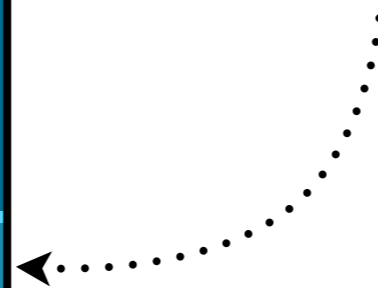




next fit:

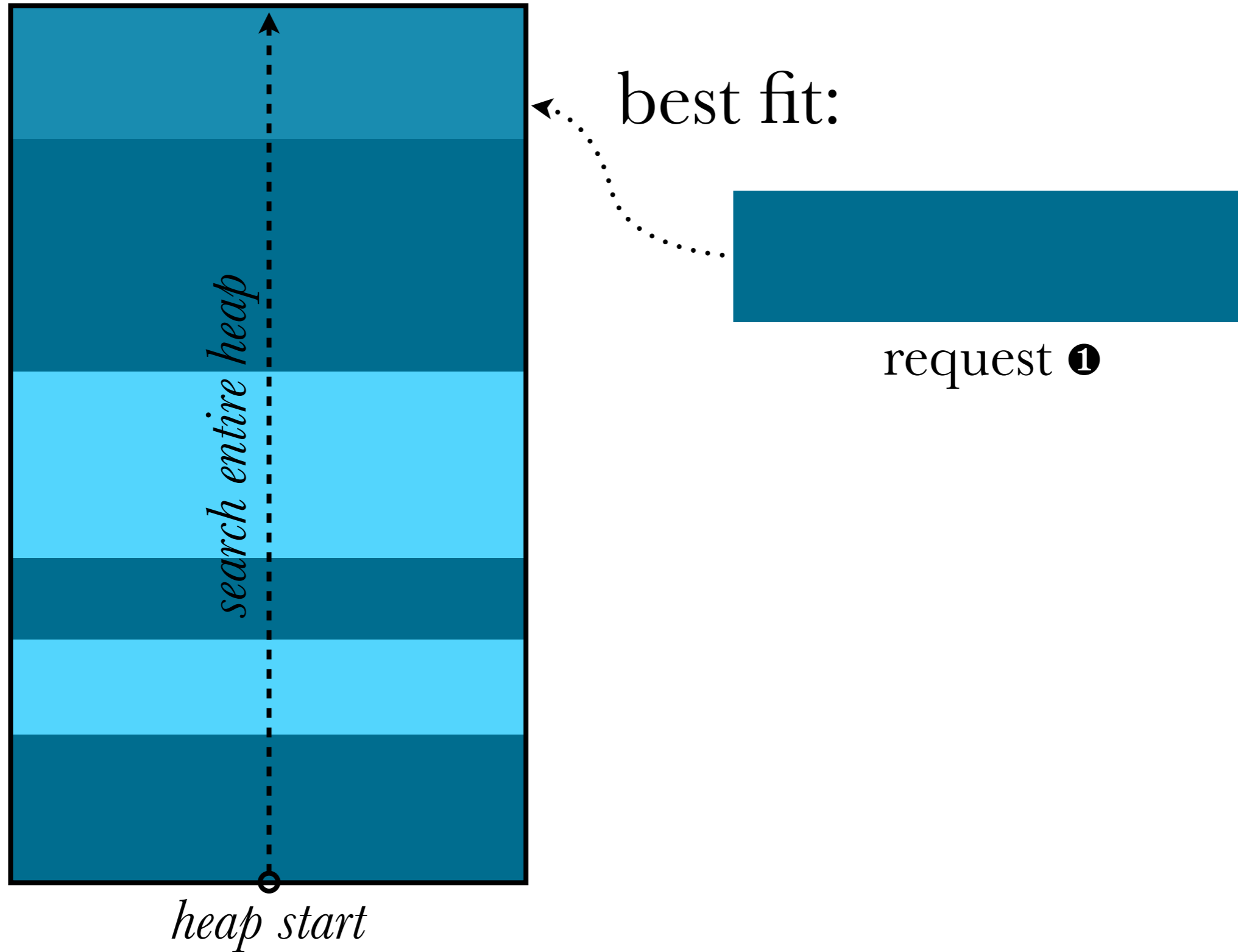


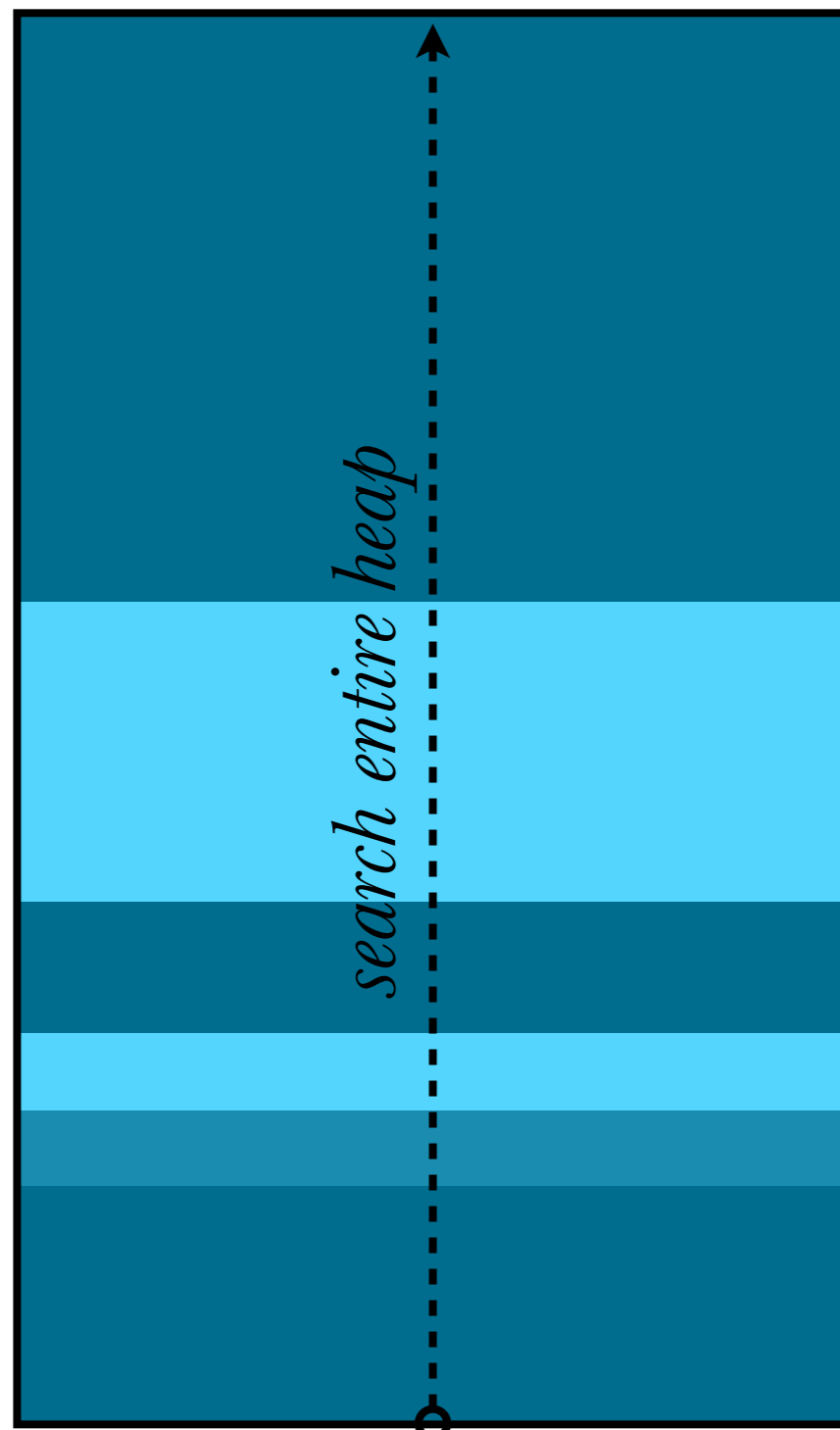
request ②



*heap start*







best fit:

request ②

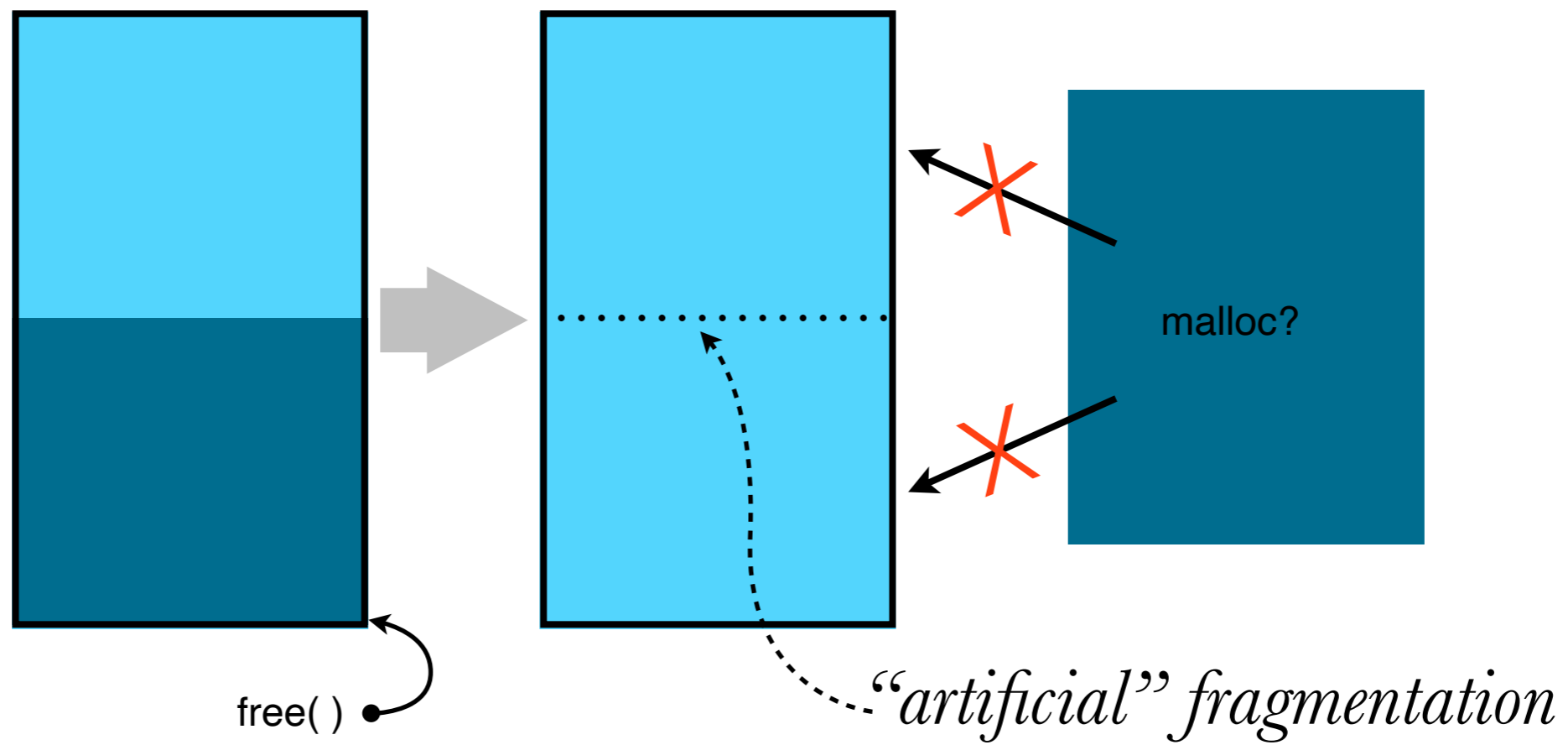
*heap start*



- intuitively, best fit *likely* improves utilization
- but at the expense of throughput and higher likelihood of scattering blocks
  - note: “best fit” is not a complete strategy
    - what to do in case of a tie?



```
void free(void *ptr) {  
    size_t *header = (char *)ptr - SIZE_T_SIZE;  
    *header = *header & ~1L;  
}
```



need to *coalesce* adjacent free blocks

have a choice of when to do this:

1. at search time: *deferred* coalescing
2. when freeing: *immediate* coalescing



# 1. deferred coalescing

```
void *find_fit(size_t size) {
    size_t *header = heap_start(),
           *next;
    while (header < heap_end()) {
        if (!(*header & 1)) {
            if (*header >= size)
                return header;
            next = (char *)header + *header;
            // merge with next block if available & free
            if (next < heap_end() && !(*next & 1)) {
                *header += *next;
                continue;
            }
        }
        header = (char *)header + (*header & ~1L);
    }
    return NULL;
}
```

to pick up all free blocks, requires the entire heap to be searched from the start



# 1. deferred coalescing

```
void *find_fit(size_t size) {
    size_t *header = heap_start(),
           *next;
    while (header < heap_end()) {
        if (!(*header & 1)) {
            if (*header >= size)
                return header;
            next = (char *)header + *header;
            // merge with next block if available & free
            if (next < heap_end() && !(*next & 1)) {
                *header += *next;
                continue;
            }
        }
        header = (char *)header + (*header & ~1L);
    }
    return NULL;
}
```

also may result in a cascade of merges  
during search — *indeterminate performance*





## 2. immediate coalescing

```
void free(void *ptr) {
    size_t *header = (char *)ptr - SIZE_T_SIZE,
        *next;
    *header = *header & ~1L;

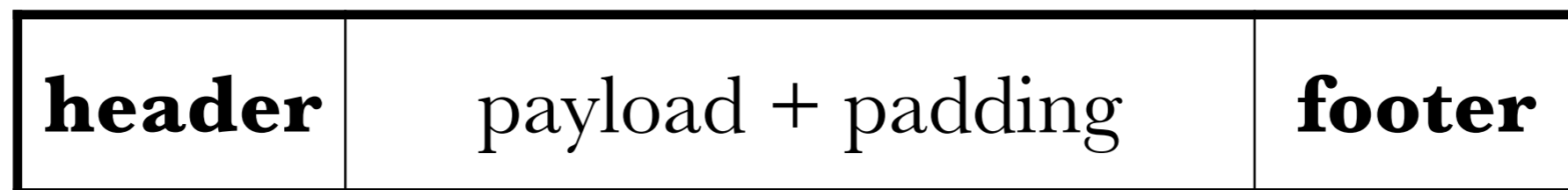
    // coalesce if possible
    next = (char *)header + *header;
    if (next <= heap_end() && !(*next & 1)) {
        *header += *next;
    }
}
```

but what about the previous block?

— can't get to it! (singly-linked list issues)

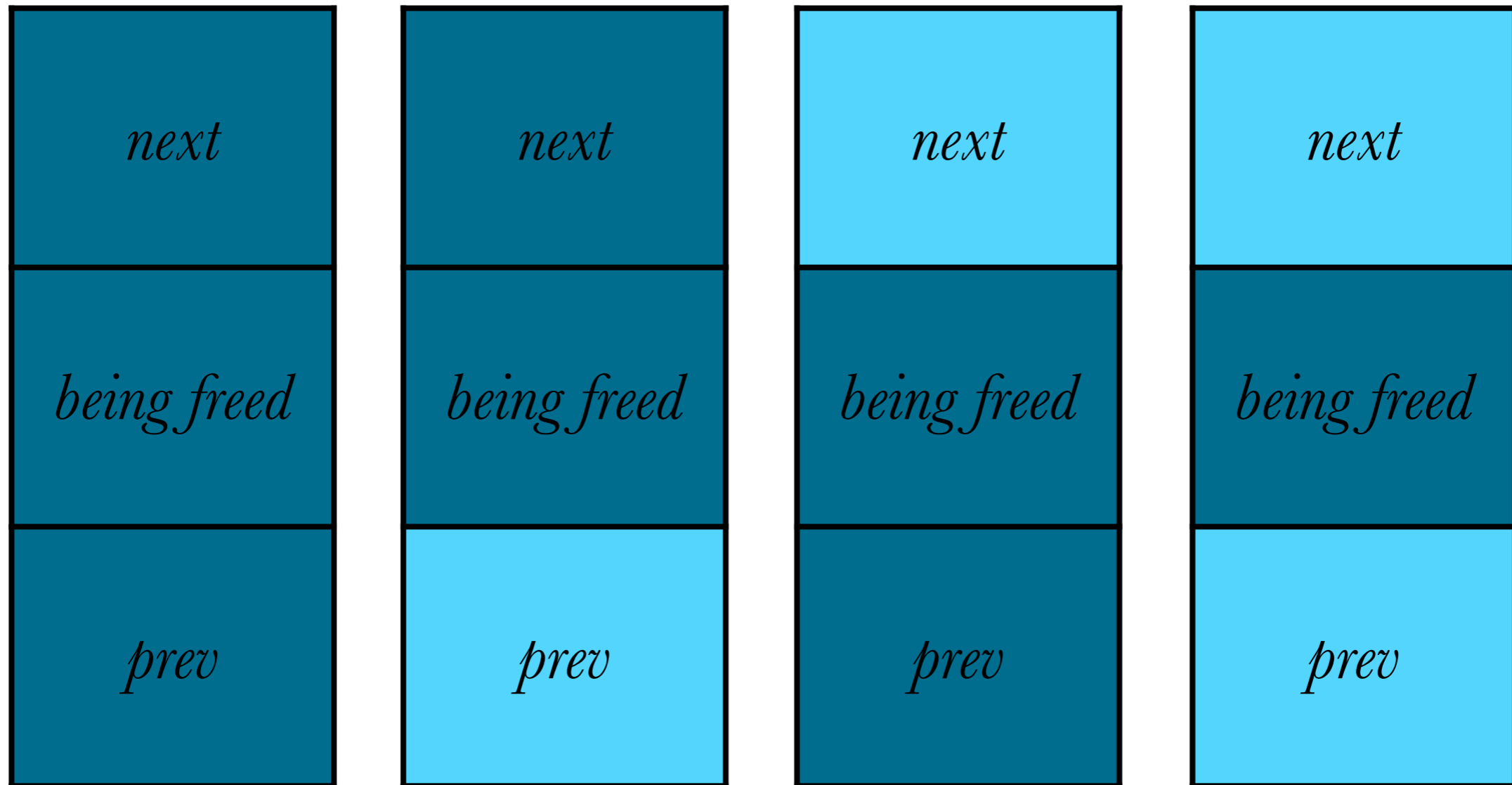


update block structure: include footer  
to support bi-directional navigation



referred to as block “boundary tags”





4 scenarios; coalescing =  $O(1)$  operation



```
// given pointer to free block header, coalesce with adjacent blocks
// and return pointer to coalesced block
void *coalesce(size_t *bp) {
    size_t *next = (char *)bp + *bp,
            *prev = (char *)bp - (*(size_t *)((char *)bp - SIZE_T_SIZE) & ~1L);
    int next_alloc = *next & 1, // FIXME: potential segfault!
        prev_alloc = *prev & 1, // FIXME: potential segfault!

    if (prev_alloc && next_alloc) {
        return bp;
    } else if (!prev_alloc && next_alloc) {
        *prev += *bp; // header
        *(size_t *)((char *)bp + *bp - SIZE_T_SIZE) = *prev; // footer
        return prev;
    } else if (prev_alloc && !next_alloc) {
        ...
    } else {
        ...
    }
}
```



```
// given pointer to free block header, coalesce with adjacent blocks
// and return pointer to coalesced block
void *coalesce(size_t *bp) {
    size_t *next, *prev;
    int next_alloc, prev_alloc;

    // must deal with edge cases!
    if (heap_start() < bp) {
        prev = (char *)bp - (*(size_t *)((char *)bp-SIZE_T_SIZE) & ~1L)
        prev_alloc = *prev & 1;
    } else {
        prev_alloc = 1; // sane choice
    }

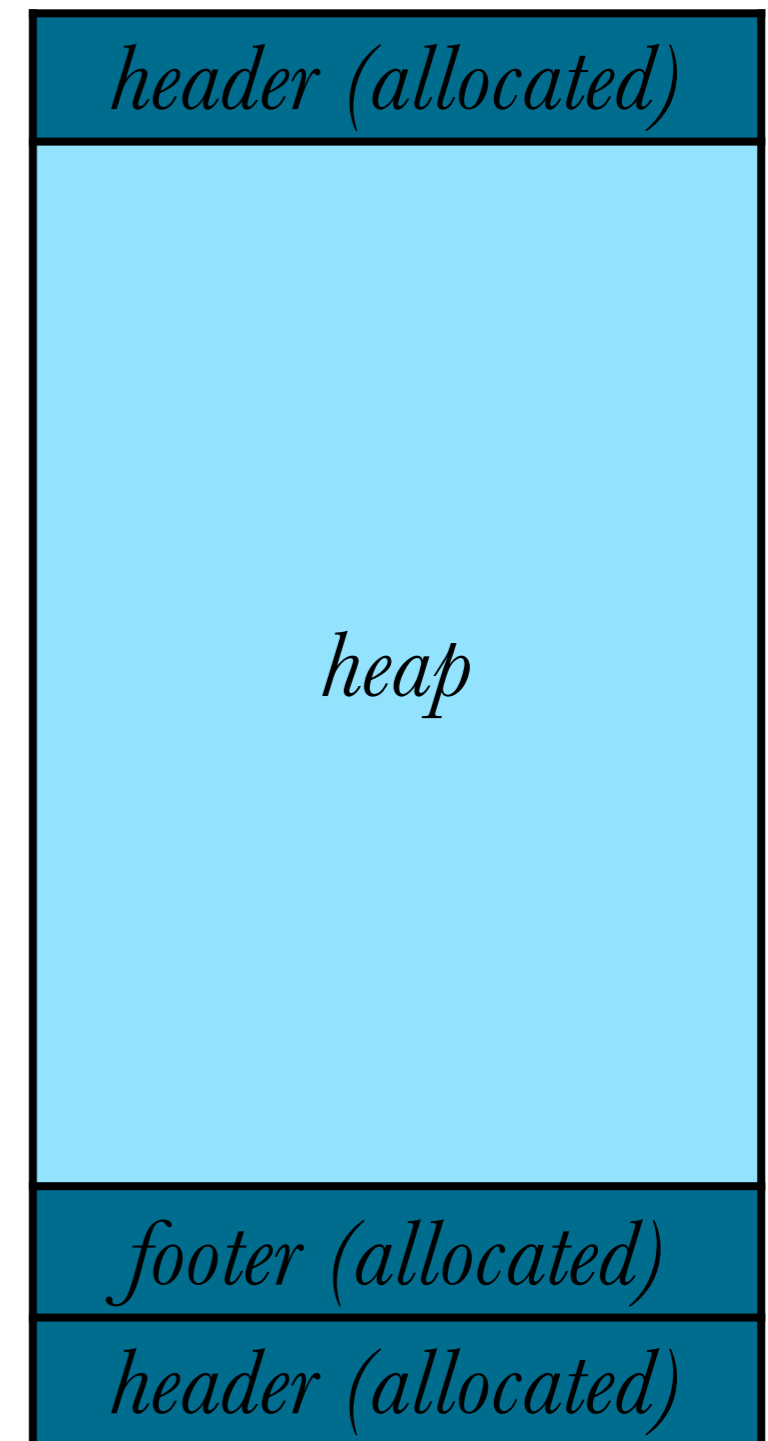
    // same for next and next_alloc

    ...
}
```



edge cases arise everywhere!  
convenient to introduce  
*sentinel prologue & epilogue blocks*

- simplify test cases
- create on heap init and  
move on expansion



# finally, realloc:

```
void *realloc(void *ptr, size_t size) {  
    // note: not dealing with footers  
    size_t *header = (size_t *)((char *)ptr - SIZE_T_SIZE);  
    size_t oldsize = *header & ~1L,  
          newsize = ALIGN(size + SIZE_T_SIZE);  
    void *newptr;  
  
    if (oldsize >= newsize) {  
        return ptr;  
    } else {  
        newptr = malloc(size);  
        memcpy(newptr, ptr, oldsize - SIZE_T_SIZE);  
        free(ptr);  
        return newptr;  
    }  
}
```



```
newptr = malloc(size);  
memcpy(newptr, ptr, oldsize - SIZE_T_SIZE);  
free(ptr);
```

=  $O(n)$  malloc,  $n$  = total # blocks  
+  $O(m)$  copy,  $m$  = size of payload

very expensive! (and `realloc` is intended to  
provide room for optimization)





ideas for optimization:

- try to “grow” block in place
  - always possible if at end of heap
- *pre-allocate* more than required; quite reasonable if already **realloc**'d
  - but should this be a DMA concern?



# **Demo:** malloc lab & realloc\* tracefiles



implicit-list summary:

- $O(n)$  malloc;  $n = \text{total \# blocks}$
- $O(1)$  free (with immediate coalescing)
- $O(n+m)$  realloc;  $n$  driven by malloc,  
 $m$  payload size



would greatly improve performance  
to search *only free blocks*



use an *explicit list*

i.e., store size & pointers in free blocks to  
create a doubly-linked list

note: allocated blocks still store just size  
& allocated bit



```
typedef struct free_blk_header {
    size_t size;
    struct free_blk_header *next;
    struct free_blk_header *prior;
} free_blk_header_t;

// init heap with a permanent (circular) free list head
void init_heap() {
    free_blk_header_t *bp = sbrk(ALIGN(sizeof(free_blk_header_t)));
    bp->size = 0;
    bp->next = bp;
    bp->prior = bp;
}

void *malloc(size_t size) {
    // instead of the following, use mm_init in the malloc lab!
    static int heap_init = 0;
    if (!heap_init) {
        heap_init = 1;
        init_heap();
    }
    ...
}
```



```
typedef struct free_blk_header {
    size_t size;
    struct free_blk_header *next;
    struct free_blk_header *prior;
} free_blk_header_t;

void *find_fit(size_t length) {
    free_blk_header_t *bp = heap_start();
    for (bp = bp->next; bp != heap_start(); bp = bp->next) {
        // find first fit
        if (bp->size >= length) {
            // remove from free list and return
            bp->next->prior = bp->prior;
            bp->prior->next = bp->next;
            return bp;
        }
    }
    return NULL;
}
```



```
// blocks must be able to accommodate a free block header
#define MIN_BLK_SIZE ALIGN(sizeof(free_blk_header_t))

void *malloc(size_t size) {

    // init_heap stuff from before goes here

    size_t *header;
    int blk_size = ALIGN(size + SIZE_T_SIZE);

    blk_size = (blk_size < MIN_BLK_SIZE)? MIN_BLK_SIZE : blk_size;

    header = find_fit(blk_size);
    if (header) {
        *header = ((free_blk_header_t *)header)->size | 1;
        // *header = *header | 1; <-- also works (why?)

        // FIXME: split if possible
    } else {
        header = sbrk(blk_size);
        *header = blk_size | 1;
    }
    return (char *)header + SIZE_T_SIZE;
}
```





when freeing (or splitting), must manually add freed block to the explicit list (vs. just updating allocated bit in implicit list)



```
void free(void *ptr) {
    free_blk_header_t *header = (char *)ptr - SIZE_T_SIZE,
        *free_list_head = heap_start();

    // add freed block to free list after head
    header->size = *(size_t *)header & ~1L;

    // add freed block to free list after head
    header->next = free_list_head->next;
    header->prior = free_list_head;
    free_list_head->next = free_list_head->next->prior = header;

    // FIXME: coalesce! (requires adding footers, too)
}
```



adding freed block at head = LIFO search

other policies: FIFO & address ordered

but search is always  $O(n)$ ,  $n = \# \text{ free blocks}$   
(linear linked structure)

*(still a huge potential throughput  
increase over implicit list!)*



how to improve search speed (esp. best-fit)?



can make this arbitrarily complex:

```
typedef struct free_blk_header {  
    size_t size;  
    struct free_blk_header *next;  
    struct free_blk_header *prior;  
} free_blk_header_t;
```

e.g., for a tree structure:

```
typedef struct free_blk_header {  
    size_t size;  
    struct free_blk_header *parent;  
    struct free_blk_header *left;  
    struct free_blk_header *right;  
} free_blk_header_t;
```



we can view this as a straightforward data  
structure implementation

but this is a perilous path!

— distances us from the problem domain



some domain-specific issues:

- real-world programs (that use the allocator) exhibit exploitable patterns
  - e.g., allocation ramps, plateaus, peaks, and common request sizes
- locality of allocations is important!



but must also take care to not *overspecialize*  
a general-purpose allocator!

viz., “*premature optimization is the root of  
all evil*” (D. Knuth)

— different programs will likely exhibit  
different request patterns/distributions





other common implementation strategies:

1. simple segregated storage
2. segregated fits

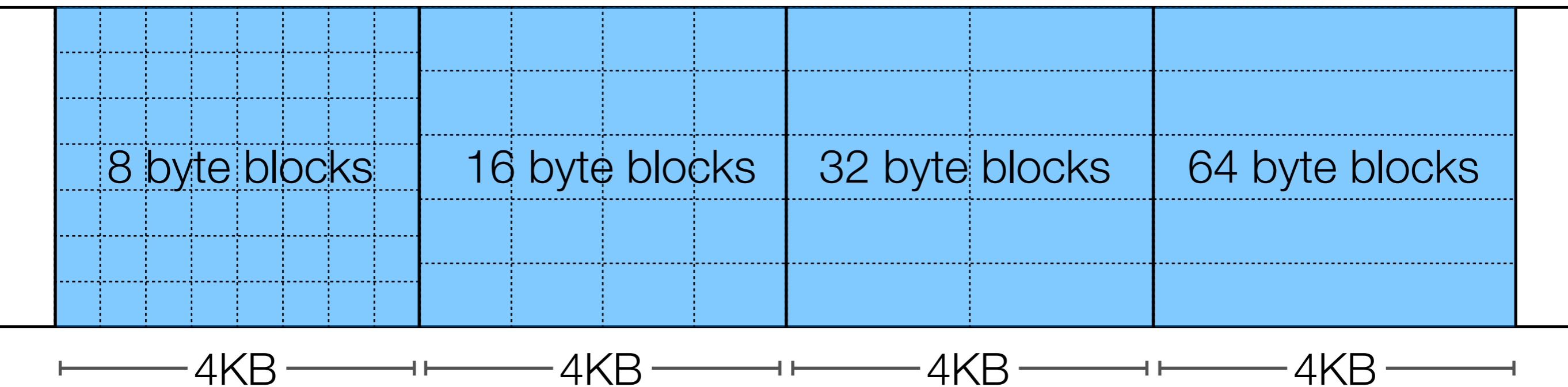


# 1. *simple segregated storage*

- pre-allocate lists of fixed block sizes in separate regions of the heap
- no splitting or coalescing



# Heap



$\text{malloc}(k)$ :

- allocate first free block in list for smallest size  $\geq k$
- if list is empty, set aside a new region for blocks of matching size



free:

- mark as free; don't coalesce
- if region becomes empty, can reuse for another size

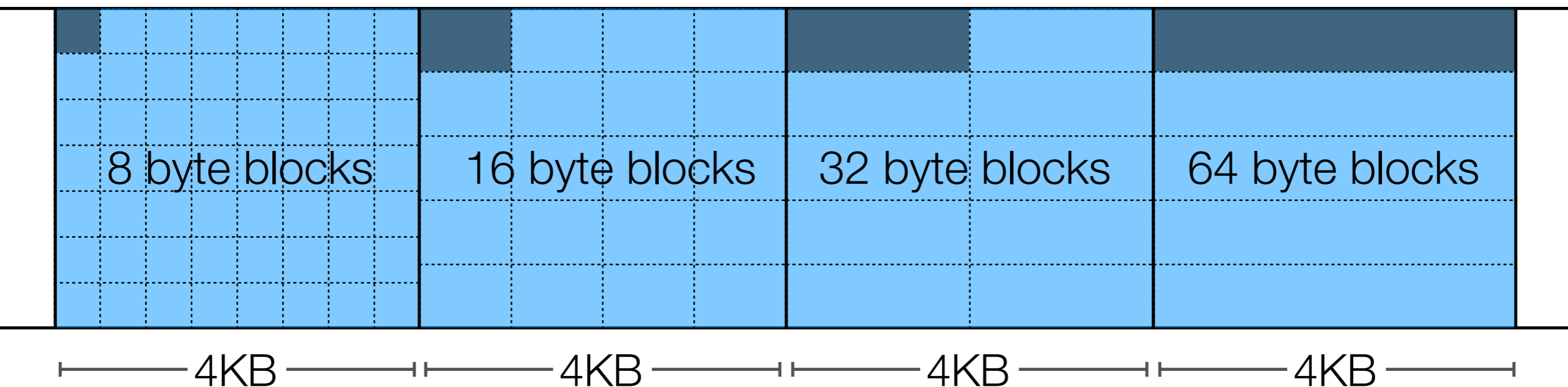


simple & fast search and allocation

also: low metadata overhead & good  
locality for similarly sized requests



tradeoff: massive fragmentation!



- by itself not a viable general-purpose allocator, but may be used to service frequent requests of predictable size
- i.e., as a “caching” allocator
  - Linux kernel internally uses something like this (known as *slab allocator*)





## 2. *segregated fits*

- maintain separate explicit free lists of varying *size classes*
- dynamically manage blocks in lists



$\text{malloc}(k)$ :

- look in list of size  $\geq k$
- allocate first empty block
- split if possible (using some threshold),  
putting leftover on appropriate list



free:

- free and, if possible, coalesce
- add block to the appropriate list (may result in moving coalesced blocks)



approximates best fit (i.e., *good* fit) with high speed by reducing search space

- may choose not to coalesce (or defer coalescing) for smaller, common sizes



```
#define NUM_SIZE_CLASSES 5

size_t min_class_size[] = { MIN_BLK_SIZE, 64, 128, 256, 1024 };

typedef struct free_blk_header {
    size_t size;
    struct free_blk_header *next;
    struct free_blk_header *prior;
} free_blk_header_t;

// global array of pointers to doubly-linked free lists
free_blk_header_t *free_lists;

void init_heap() {
    int i;
    free_lists = sbrk(NUM_SIZE_CLASSES * sizeof(free_blk_header_t));
    for (i=0; i<NUM_SIZE_CLASSES; i++) {
        free_lists[i].size = 0;
        free_lists[i].next = free_lists[i].prior = &free_lists[i];
    }
    return 0;
}
```



```
size_t min_class_size[] = { MIN_BLK_SIZE, 64, 128, 256, 1024 };
free_blk_header_t *free_lists;
```

```
void *find_fit(size_t size) {
    int i;
    free_blk_header_t *fp;
    for (i=0; i<NUM_SIZE_CLASSES; i++) {
        // locate the first suitable list that isn't empty
        if (min_class_size[i] >= size
            && free_lists[i].next != &free_lists[i]) {
            // take the first block (no searching!)
            fp = free_lists[i].next;
            // remove it from the free list
            free_lists[i].next = fp->next;
            fp->next->prior = &free_lists[i];
            // and try to split it
            try_split(fp, size);
            return fp;
        }
    }
    // FIXME: do a full search of "top" list if not found!
    return NULL;
}
```



```
size_t min_class_size[] = { MIN_BLK_SIZE, 64, 128, 256, 1024 };
free_blk_header_t *free_lists;
```

```
void try_split(free_blk_header_t *fp, size_t needed) {
    int i, remaining = fp->size - needed;
    free_blk_header_t *sp;
    if (remaining < MIN_BLK_SIZE)
        return;
    // split the block ...
    fp->size = needed;
    sp = (free_blk_header_t *)((char *)fp + needed);
    sp->size = remaining;

    // ... and put the leftover free block in the correct list
    for (i=NUM_SIZE_CLASSES-1; i>0; i--)
        if (min_class_size[i] <= remaining) {
            sp->prior = &free_lists[i];
            sp->next = free_lists[i].next;
            free_lists[i].next = free_lists[i].next->prior = sp;
            break;
        }
}
```



### 3. *buddy systems*

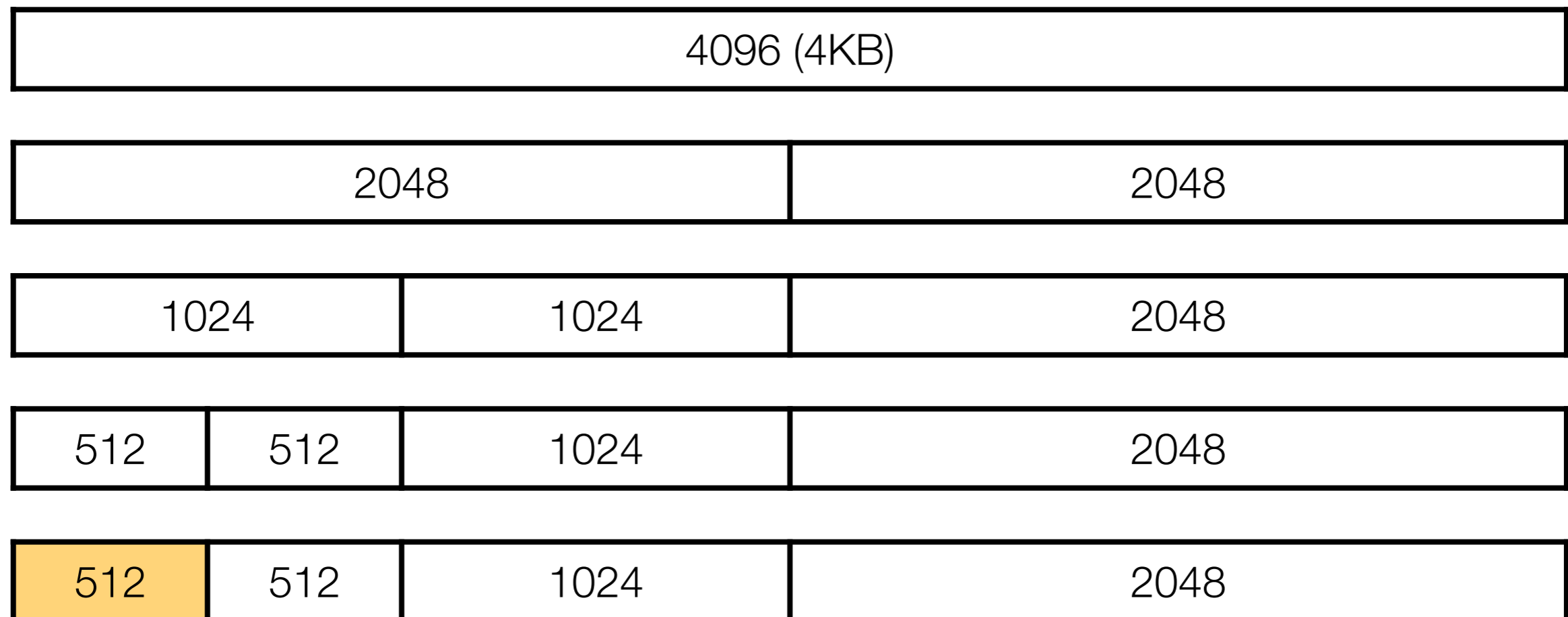
- each block (starting with the whole heap) may be split into two sub-blocks at a preset boundary



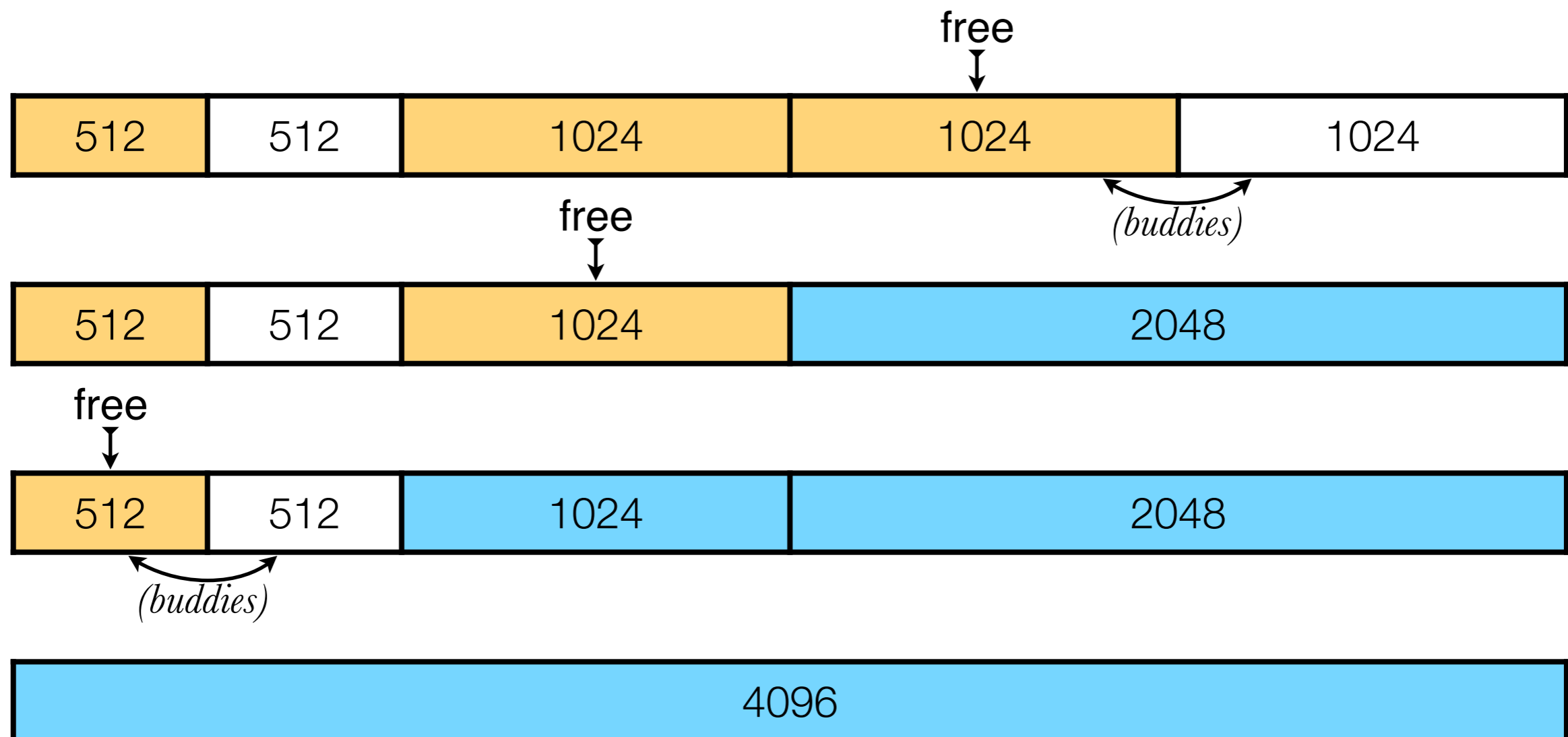


e.g., “binary buddies”

malloc(450)



e.g., “binary buddies”



# Fibonacci sequence:

1, 2, 3, 5, 8, 13, 21, 34, 55, 89, 144, 233, 377, 610, 987, 1597, 2584, 4181

e.g., “Fibonacci buddies”

malloc(450)

4181
------

1597	2584
------	------

610	987	2584
-----	-----	------



very little block overhead:

- free/allocated bit
- is block “whole” or split?
- (size not needed!)



in practice, however, internal  
fragmentation is much worse than  
segmented fits



good reading: “Doug Lea’s malloc”

<http://gee.cs.oswego.edu/dl/html/malloc.html>



hybrid allocator:

- best fit; segregated fits
  - LRU for tie-breaking
- deferred coalescing
- “mmap” for large requests

